MATHEMATICS FORMULA BOOKLET - GYAAN SUTRA

П	N		CV
П	IN	U	ᅜᄉ

S.No	o. Topic	Page No.
4	Chrainhalling	0 0
1.	Straight Line	2 – 3
2.	Circle	4
3.	P ar abol a	5
4.	El li ps	5 –6
5.	Hyperbola	6 – 7
6.	Limit of Function	8 – 9
7.	Method of Differentiation	9 – 11
8.	Application of Derivatves	11 – 13
9.	Indefinite Intedration	14 – 17
10.	Definite Integration	17 – 18
11.	Fundamental of Mathematics	19 – 21
12.	Quadratic Equation	22 – 24
13.	Sequence & Series	24 – 26
14.	Binomial Theorem	26 – 27
15.	Permutation & Combinnation	28 – 29
16.	Probability	29 – 30
17.	Complex Number	31 – 32
18.	Vectors	32 - 35
19.	Dimension	35 – 40
20.	Solution of Triangle	41 – 44
21.	Inverse Trigonometric Functions	44 – 46
22.	Statistics	47 – 49
23.	Mathematical Reasoning	49 – 50
24.	Sets and Relation	50 – 51

MATHEMATICS FORMULA BOOKLET - GYAAN SUTRA

STRAIGHT LINE

1. Distance Formula:

$$d \; \Box \sqrt{(x_1 \! - \! x)_{\!\! 2}^{\ \ \, 2} \; \Box (y_1 \! - \! y)_{\!\! 2}^{\ \ \, 2}} \; .$$

Section Formula :

$$x = \frac{mx2 \boxtimes nx1}{m \boxtimes n}$$
; $y = \frac{my2 \boxtimes ny1}{m \boxtimes n}$.

3. Centroid, Incentre & Excentre:

4. Area of a Triangle:

$$\Box ABC = \frac{1}{2} \begin{vmatrix} 1 & 1 & 1 \\ x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ 3 & y_3 & 1 \end{vmatrix}$$

5. Slope Formula:

Line Joining two points (x y) & (x y), m =
$$\underbrace{y_1 \Box y_2}_{x_1 \Box x_2}$$

6. Condition of collinearity of three points:

$$\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = 0$$

7. Angle between two straight lines:

8. Two Lines:

ax + by + c = 0 and $a \boxtimes x + b \boxtimes y + c \boxtimes = 0$ two lines

1. parallel if
$$\frac{a}{a} = \frac{b}{b} \boxtimes \frac{c}{c}$$

- 2. Distance between two parallel lines = $\frac{c1 \boxtimes c_2}{\sqrt{a2 \boxtimes b^2}}$.
- 3 Perpendicular : If $aa \boxtimes + bb \boxtimes = 0$.

9. A point and line:

- 1. Distance between point and line = $\frac{a \times 1 \square by1 \square c}{\sqrt{a2 \square b2}}$.
- 2. Reflection of a point about a line:

$$\frac{x \boxtimes x \ 1}{a} \square \frac{y \boxtimes y \ 1}{b} \square \square^2 \frac{ax}{a^2 \square b^2} \square c$$

3. Foot of the perpendicular from a point on the line is

$$\frac{x \boxtimes x1}{a} \square \frac{y \boxtimes y1}{b} \square \square \frac{ax1 \boxtimes by1 \boxtimes_{C}}{a2 \boxtimes b^2}$$

10. Bisectors of the angles between two lines:

$$\frac{ax\boxtimes by\boxtimes c}{\sqrt{a2\boxtimes b2}} \ = \pm \ \frac{a\boxtimes x\boxtimes b\boxtimes y\boxtimes c\boxtimes}{\sqrt{a\boxtimes 2\boxtimes b\boxtimes 2}}$$

11. Condition of Concurrency:

of three straight lines aix+ biy + ci = 0, i = 1,2,3 is
$$\begin{vmatrix} a_1 & b & c \\ a_2 & 1 & 1 \\ a_3 & b & c \end{vmatrix} = 0.$$

If I is the acute angle between the pair of straight lines, then tan

CI RCL E

Intercepts made by Circle $x^2 + y^2 + 2gx + 2fy + c =$ 6 on the Axes: 1.

(a)
$$2\sqrt{g^2\Box c}$$
 on x -axis (b) $2\sqrt{f2\boxtimes c}$ on y - aixs

2. Parametric Equations of a Circle:

$$x = h + r \cos \square$$
; $y = k + r \sin \square$

3. Tangent:

(a) Slope form :
$$y = mx \pm a_{1 \boxtimes m2}$$

(b) Point form : $xx + yy = a2$

(b) Point form :
$$xx + yy = a2$$
 or $T = c$

- (b) Point form: xx + yy = a2 or T = o(c) Parametric form: $x \cos x + y \sin x = a$
- 4. Pair of Tangents from a Point: $SS1 = T^2$.
- Length of a Tangent : Length of tangent is 5.
- **Director Circle:** $x^2 + y^2 = 2a^2$ for $x^2 + y^2 = a^2$ 6.
- Chord of Contact: T = 07.
 - 1. Length of chord of contact = $\frac{2LR}{\sqrt{R^2 \Box L^2}}$
 - 2. Area of the triangle formed by the pair of the tangents & its chord of

contact =
$$\frac{RL3}{R2 \boxtimes L2}$$

3. Tangent of the angle between the pair of tangents from (x1, y1)

$$= \frac{2RL}{L^2 \square R^2}$$

- 4. Equation of the circle circumscribing the triangle PT1 T2 is : $(x \boxtimes x)(x + g) + (y \boxtimes y)(y + f) = 0.$
- Condition of orthogonality of Two Circles: 2 g1 g2 + 2 f1 f2 = c1 + c2. 8.
- **Radical Axis**: SM $S_{9} = 0$ i.e. $2(g \times g2) \times + 2(f1 \times f2) y + (c1 \times c2) = 0$. 9.
- Family of Circles: S1 + KS2 = 0, S + KL = 0. 10.

PARABOLA

1. Equation of standard parabola :

 y^2 4ax, Vertex is (0, 0), focus is (a, 0), Directrix is x + a = 0 and Axis is y = 0. Length of the latus rectum = 4a, ends of the latus rectum are L(a, 2a) & L' (a, \mathbb{Z} 2a).

- 2 Parametric Representation: $x = at^2 & y = 2at$
- . Tangents to the Parabola $y^2 = 4ax$:
- 3 1. Slope form $y = mx + \frac{a}{m}$ (m \boxtimes 0)2. Parametric form ty = x + at2
- 3. Point form T = 0
- 4. Normals to the parabola $y^2 = 4ax$:

$$y \boxtimes y_1 = \boxtimes \frac{y_1}{2a}$$
 (x \overline{\text{x}} 1) at (x1, y1); $y = mx \boxtimes 2am \boxtimes am3$ at (am2) \overline{\text{2am}};
y + tx = 2at + at3 at (at, 2at).

ELLIPSE

1. Standard Equation: $\frac{x^2}{a^2} \Box \frac{y^2}{b^2} = 1$, where $a > b \& b^2 = a^2 (1 \boxtimes e^2)$.

Eccentricity:
$$e = \sqrt{1 \boxtimes \frac{b^2}{a^2}}$$
, $(0 < e < 1)$, Directrices : $x = \pm \frac{a}{e}$.

Focii: $S \boxtimes (\pm a \quad e, 0)$. Length of, major axes = 2a and minor axes = 2b **Vertices**: $A \boxtimes \boxtimes (\boxtimes a, 0) \& A \boxtimes (a, 0)$.

Latus Rectum : =
$$\frac{2b2}{a}$$
 $\boxtimes 2a$ $\boxtimes 1$ $\boxtimes e2$

- 2 Auxiliary Circle: $x^2 + y^2 = a^2$
- . Parametric Representation : $x = a \cos \mathbb{Z} \& y = b \sin \mathbb{Z}$
- Position of a Point w.r.t. an Ellipse:

The point P(x1, y1) lies outside, inside or on the ellipse according as;

$$\frac{x_1^2}{a^2} \Box \frac{y_1^2}{b^2} \Box 1 > < \text{or} = 0.$$

5. Line and an Ellipse:

The line y = mx + c meets the ellipse $\frac{x}{2} \Box \frac{y}{2} = 1$ in two points real, coincident or imaginary according as $c^2 \stackrel{\text{def}}{2} < = \frac{\text{lor}}{2} > a^2 \text{m}^2 + b^2$.

6. Tangents:

Slope form: y = mx ± $\sqrt{a2m2\Box b^2}$, Point form : $\frac{xx_1}{a^2}\Box \frac{yy_1}{b^2}\Box 1$,

Parametric form: $\frac{x\cos\Box}{a}\Box\frac{y\sin\Box}{b}\boxtimes 1$

7. Normals:

 $\frac{a2x}{x1} \,\square \frac{b2y}{y1} \,= a^2 \,\boxtimes \, b^2, \, ax. \, \, sec \,\square \, \, \square by. \, \, cosec \, \, \boxtimes = (a^2 \,\boxtimes \, b^2), \, y = mx \, \, \boxtimes \, \frac{ \, \square \, b2 \, \square \, m}{\sqrt{a^2 \,\square \, b2 m2}} \,.$

8. Director Circle: $x^2 + y^2 = a^2 + b^2$

HYPERBOLA

1. Standard Equation:

Standard equation of the hyperbola is $\frac{x^2}{a} \Box \frac{y}{2} \Box 1$, where b2 = a2 (e2 \blacksquare).

Focii: $S \boxtimes (\pm ae, 0)$ Directrices: $x = \pm \frac{a}{e} 2$

Vertices : A ⊠(± a, 0)

Latus Rectum ($^{\boxtimes}$): $^{\square}$ $\stackrel{\triangle}{=}$ $\frac{2b2}{a}$ = 2a (e2 \square 1).

2. Conjugate Hyperbola:

 $\frac{x^2}{a^2}\Box_{02}^{y^2}\Box_1$ & $\Box_{a_2}^{x^2}\Box_{02}^{y^2}\Box_1$ are conjugate hyperbolas of each.

3 Auxiliary Circle:
$$x2 + y2 = a2$$
.

. Parametric Representation: x = a sec □ & y = b tan ⊠

4

5. Position of A Point 'P' w.r.t. A Hyperbola:

 $s^1 = \frac{y_1^2}{a^2} = \frac{y_1^2}{b^2} = 1$, = or < 0 according as the point (x1, y1) lies inside, on or outside the curve.

6. Tangents:

- (i) Slope Form : $y = m x \sqrt{a2m2 b2}$
- (ii) Point Form: at the point (x1, y1) is $\frac{xx_1}{a^2} \Box \frac{yy_1}{b^2} \Box 1$.
- (i ii) Parametric Form : $\frac{x \sec \Box y \tan \Box x}{a}$ 1.

7. Normals:

- (a) at the point P (x1, y1) is $\frac{a2x}{x1} \Box \frac{b2y}{y1} = a2 + b2 = a2 e2$.
- (b) at the point P (a sec \boxtimes , b tan \boxtimes) is $\frac{ax}{\sec\Box} = \frac{by}{\tan\Box} = a2 + b2 = a2 = 2$.
- (c) Equation of normals in terms of its slope 'm' are y $= mx \boxtimes \sqrt{\frac{a^2}{a^2} \square b^2 m^2}.$

8. Asymptotes:
$$\overset{X}{a} \Box \overset{Y}{b} \boxtimes 0$$
 and $\overset{X}{a} \Box \overset{Y}{b} \boxtimes 0$

Pair of asymptotes : $\frac{x^2}{a^2} \Box \frac{y^2}{b^2} \boxtimes 0$.

9. Rectangular Or Equilateral Hyperbola: xy = c2, eccentricity is $\sqrt{2}$. Vertices: $(\pm C\sqrt{2})$ Consideration $(\pm C\sqrt{2}$

Latus Rectum (I): $\boxtimes = 2\sqrt{2}$ c = T.A. = C.A.

Parametric equation x = ct, y = c/t, $t \boxtimes R - \{0\}$

Equation of the tangent at P (x, 1y1) is $\frac{x}{x_1} \frac{y}{y_1} = 2 \& at P(t)$ is $\frac{x}{t} + t y = 2 c$.

Equation of the normal at P (t) is x t3 \boxtimes y t = c (t4 \boxtimes 1).

Chord with a given middle point as (h, k) is kx + hy = 2hk.

LIMIT OF FUNCTION

1. Limit of a function f(x) is said to exist as $x \square$ a when,

$$\underset{h\boxtimes 0}{\text{Limit }} f (a \boxtimes h) = \underset{h\square}{\text{Lim it }} f (a + h) = \text{some finite value M.}$$

(Left hand limit) (Right hand limit)

2. Indeterminant Forms:

3. Standard Limits:

$$\lim_{x \to 0} it \frac{\sin x}{x} = \lim_{x \to 0} it \frac{\tan x}{x} = \lim_{x \to 0} it \frac{\tan x}{x}$$

$$= \underset{x \boxtimes 0}{\text{Limit}} \frac{\sin \boxtimes 1x}{x} = \underset{x}{\text{Lim}} \text{ it } \frac{ex \boxtimes 1}{x} = \underset{x}{\text{Lim}} \text{ it } \frac{\boxtimes n(1 \boxtimes x)}{x} = 1$$

$$\lim_{x \to 0} it (1+x)^{1/x} = \lim_{x \to 0} it \left[\frac{1}{x} \right] \left[\frac{1}{x} \right] = e, \quad \lim_{x \to 0} it \frac{ax \times 1}{x} = logea, a > 0,$$

$$\underset{\mathbf{x} \square \mathbf{a}}{\text{Lim}} \text{ it } \frac{\mathbf{x} \mathbf{n} \square \mathbf{a} \mathbf{n}}{\mathbf{x} \square \mathbf{a}} = \mathbf{n} \mathbf{a}^{\mathsf{n}-1}.$$

4. Limits Using Expansion

(i)
$$a^{x} \Box 1 \Box \frac{x \ln a}{1!} \Box \frac{x 2 \ln 2}{2!} \Box \frac{x 3 \ln 3}{3!} \Box \dots a \Box 0$$

(ii)
$$e^{x} \Box 1 \Box \frac{x}{11} \Box \frac{x2}{2!} \Box \frac{x3}{3!} \Box \dots$$

(iii) In
$$(1+x) = {x \over 2} \square \frac{x^2}{3} \square \frac{x^4}{4} \boxtimes \dots$$
 for $\square 1 \square_X \square 1$

(iv)
$$\sin x \Box x \Box \frac{x3}{3!} \Box \frac{x5}{5!} \Box \frac{x7}{7!} \boxtimes \dots$$

$$(v) \qquad \text{cosx} \ \square \ \square \frac{x^2}{2!} \ \square \frac{x^4}{4!} \ \square \frac{x^6}{6!} \boxtimes \dots.$$

(vi)
$$\tan x = x \boxtimes \frac{x3}{3} \square \frac{2x5}{15} \boxtimes \dots$$

(vii) for
$$|x| < 1$$
, $n \square R (1 + x)n$

= 1 + nx +
$$\frac{n(n \boxtimes 1)}{1.2}$$
 x2 + $\frac{n(n \boxtimes 1)(n \boxtimes 2)}{1.2.3}$ x3 +

5. Limits of form $1 \boxtimes$, $00, \boxtimes \mathbf{0}$

Also for (1) type of problems we can use following rules.

$$\lim_{x \to 0} (1 + x)1/x = e, \lim_{x \to a} [f(x)]g(x) ,$$

where
$$f(x)$$
 \Box 1 ; $g(x)\Box\Box\Box\bar{a}s\;x\;\Box\;a=\;e^{\lim[f(x)\boxtimes 1]g(x)}$

6. Sandwich Theorem or Squeeze Play Theorem:

If
$$f(x) \square g(x) \square h(x) \square x \&$$
 Limit $f(x) = \mathbb{N} = \text{Limit h(x) then Limit } g(x) = \square .$

METHOD OF DIFFERENTIATION

1. Differentiation of some elementary functions

1.
$$\frac{d}{dx}(xn) = nx^{n-1}$$

$$\frac{d}{3. dx} (|x|) = \frac{1}{x}$$

5.
$$\frac{dx}{dx}$$
 (sin x) = cos x

9.
$$\frac{dx}{}$$
 (tan x) = sec2 x

2.
$$\frac{d}{dx}$$
 (ax) = ax \(\text{In a} \)

$$4. \boxtimes_{\frac{d}{dx}}^{d} (logax) = \frac{1}{x \boxtimes na}$$

6.
$$\frac{dx}{d}(\cos x) = -\sin x$$

8.
$$\longrightarrow$$
 (cosec x) = - cosec x cot x

10.
$$\frac{d}{dx}$$
 (cot x) = - cosec2 x

2. Basic Theorems

1.
$$\frac{d}{dx}$$
 $(f \pm g) = f\boxtimes(x) \pm g\boxtimes(x)$ 2. $\frac{d}{dx}$ $(k f(x)) = k \frac{d}{dx}$ $f(x)$

3.
$$\frac{d}{dx}$$
 (f(x) . g(x)) = f(x) g\(\text{M}(x) + g(x) \) f\(\text{M}(x)

4.
$$\frac{d}{dx}$$
 $\frac{d}{g(x)} = \frac{g(x)f\boxtimes(x)\boxtimes f(x)g\boxtimes(x)}{g2(x)}$ 5. $\frac{d}{dx}$ $(f(g(x))) = f\boxtimes(g(x)) g\boxtimes(x)$

Derivative Of Inverse Trigonometric Functions.

$$\frac{d\sin -1x}{dx} = \frac{1}{\sqrt{1 \boxtimes x^2}}, \frac{d\cos -1x}{dx} = -\frac{1}{\sqrt{1 \boxtimes x^2}}, \text{ for } -1 < x < 1.$$

$$\frac{dtan-1x}{dx} = \frac{1}{1 \boxtimes x2}, \frac{d \cot -1}{dx} = -\frac{1}{1 \boxtimes x2} (x \square R)$$

$$\frac{d \sec -1}{dx} = \frac{1}{|x| \sqrt{x2 \boxtimes 1}}, \frac{d \cos e \bar{c}^{-1} x}{dx}$$

$$= -\frac{1}{|x|\sqrt{x^2\Box 1}}, \text{ for } x\Box (-\Box, -1)\Box (1, \boxtimes)$$

3. Differentiation using substitution

Following substitutions are normally used to simplify these expression.

(i)
$$\sqrt{x2 \boxtimes a2}$$
 by substituting $x = a \tan \boxtimes$, where $-\frac{\square}{2} < \square \square \square$

(ii)
$$\sqrt{a^2 \square x^2}$$
 by substituting $x = a \sin \square$, where $-\frac{\square}{2} \square \square \square$

(iii)
$$\sqrt{x^2 \Box a^2}$$
 by substituting $x = a \sec \mathbb{Z}$, where $\Box \Box \Box \Box$, $\Box \Box$

(iv)
$$\sqrt{\frac{x \Box a}{a \Box x}}$$
 by substituting $x = a \cos \Box$, where $\Box \Box \bigcirc \Box$.

4. Parametric Differentiation

If
$$y = f(\square) \& x = g(\boxtimes)$$
 where \square is a parameter, then $\frac{dy}{dx} \square \frac{dy/d\square}{dx/d\square}$.

5. Derivative of one function with respect to another

Let
$$y = f(x)$$
; $z = g(x)$ then $\frac{d}{y} \Box \frac{dy}{dx} \frac{f'(x)}{g'(x)}$
 $\frac{f'(x)}{g'(x)}$

6. If
$$F(x) = \begin{vmatrix} f(x) g(x) & h(\overline{x}) \\ I(x) m(x) & n(x) \\ u(x) v(x) & w(x) \end{vmatrix}$$
, where f, g, h, I, m, n, u, v, w are differentiable

$$\text{functions of x then F} \quad \square(\overline{x}) = \begin{vmatrix} f'(x) \ g'(x) & h'(x) \\ I(x) \ m(x) & n(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & n'(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & w(x) \end{vmatrix} + \begin{vmatrix} f(x) \ g(x) & h(x) \\ I'(x) \ m'(x) & h(x) \\ u(x) \ v(x) & h(x) \\$$

$$f(x)$$
 $g(x)$ $h(x)$ $I(x)$ $m(x)$ $n(x)$ $u'(x)$ $v'(x)$ $w'(x)$

APPLICATION OF DERIVATIVES

1. Equation of tangent and normal

Tangent at (x^1, y^1) is given by $(y - y^1) = f\boxtimes(x^1)$ $(x - x^1)$; when, $f\boxtimes(x^1)$ is real.

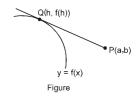
And normal at
$$(x, y)$$
 is $(y - y1) = -\frac{1}{f \boxtimes (x1)} (x - x)$, when $f(x)$ is nonzero

real.

2. Tangent from an external point

Given a point P(a, b) which does not lie on the curve y = f(x), then the equation of possible tangents to the curve y = f(x), passing through (a, b) can be found by solving for the point of contact Q.

$$f\boxtimes(h) = \frac{f(h)\boxtimes b}{h\boxtimes a}$$

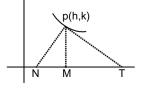


And equation of tangent is $y - b = \frac{f(h) \boxtimes b}{h \boxtimes a} (x - a)$

3. Length of tangent, normal, subtangent, subnormal

(i) PT =
$$|\mathbf{k}| \sqrt{1 \Box \frac{1}{m2}}$$
 = Length of Tangent

(ii)
$$PN = |k| \sqrt{1 \boxtimes m2} = Length of Normal$$



(iii)
$$TM = \left| \frac{k}{m} \right| = Length of subtangent$$

(iv) MN = |km| = Length of subnormal.

4. Angle between the curves

Angle between two intersecting curves is defined as the acute angle between their tangents (or normals) at the point of intersection of two curves (as shown in figure).

$$\tan \boxtimes = \begin{vmatrix} m \boxtimes m2 \\ 1 \boxtimes m_1 m2 \end{vmatrix}$$

5. Shortest distance between two curves

Shortest distance between two non-intersecting differentiable curves is always along their common normal.

(Wherever defined)

Rolle's Theorem :

If a function f defined on [a, b] is

- (i) continuous on [a, b]
- (ii) derivable on (a, b) and
- (iii) f(a) = f(b),

then there exists at least one real number c between a and b (a < c < b) such that $f\boxtimes(c)=0$

7. Lagrange's Mean Value Theorem (LMVT):

If a function f defined on [a, b] is

(i) continuous on [a, b] and (ii) derivable on (a, b) then there exists at least one real numbers between a and b (a < c < b) such

that
$$\frac{f(b) \Box f(a)}{b \Box a} = f \boxtimes (c)$$

8. Useful Formulae of Mensuration to Remember :

- 2. Surface area of cuboid = $2(\boxtimes b + bh + h\boxtimes)$.
- 3. Volume of cube = a3
- 4. Surface area of cube = 6a2
- 5. Volume of a cone = $\frac{1}{3} \frac{2}{||\mathbf{M}||^2} \mathbf{h}$. Curved surface area of cone = $||\mathbf{M}|| \mathbf{M}|$ ($|\mathbf{M}|$ = slant height)
- 6. Curved surface area of a cylinder = $2 \boxtimes rh$.
- 7. Total surface area of a cylinder = 2Nrh + 2Nr2.
- 8.
- 9. Volume of a sphere = $\frac{4}{3\text{Mr}}$.
- Surface area of a sphere = 4 Mr 2.
- 11. Area of a circular sector = $\frac{1}{2}$ r2 \boxtimes , when \boxtimes is in radians.
- 12. Volume of a prism = (area of the base) \times (height).
- 13. Lateral surface area of a prism = (perimeter of the base) × (height).
- Total surface area of a prism = (lateral surface area) + 2 (area of the base)(Note that lateral surfaces of a prism are all rectangle).
- **15.** Volume of a pyramid = $\frac{1}{3}$ (area of the base) × (height).
- 16. Curved surface area of a pyramid = $\frac{1}{2}$ (perimeter of the base) × (slant height). (Note that slant surfaces of a pyramid are triangles).

INDEFINITE INTEGRATION

1. If f & g are functions of x such that g(x) = f(x) then,

2. Standard Formula:

(iv)
$$\Box_{a^{px+q}} dx = \frac{1}{p} \Box_{na} + c; a > 0$$

(v)
$$\sin (ax + b) dx = \Box \frac{1}{a} \cos (ax + b) + c$$

(vi)
$$\cos (ax + b) dx = \frac{1}{a} \sin (ax + b) + c$$

(v i i)
$$\int \tan(ax + b) dx = \frac{1}{a} \ln \sec(ax + b) + c$$

(ix)
$$\sec^2 (ax + b) dx = \frac{1}{a} \tan(ax + b) + c$$

(xi)
$$\int \sec x \, dx = \ln (\sec x + \tan x) + c$$
 OR $\ln \tan \frac{x}{2} + c$

(xv)
$$\frac{\Box}{[|x|]\sqrt{x2\boxtimes a2}} = \frac{1}{a} \sec \frac{x}{a} + c$$

(xviii)
$$\frac{\int dx}{a2 \ \Box \ x} = \frac{1}{2a} \ |a| \left| \frac{a \boxtimes x}{a \boxtimes x} \right| + c$$

(xix)
$$\frac{\int dx}{x^2 \ln a} = \frac{1}{2a} \ln \left| \frac{x \times a}{x \times a} \right| + c$$

(xx)
$$\sqrt{a2 \square x} 2dx = \frac{x}{2} \sqrt{a^2 \square x^2} + \frac{a2}{2} \sin \frac{x}{a} + c$$

3. Integration by Substitutions

If we substitute f(x) = t, then $f \ (x) = t$

4. Integration by Part:

Make the substitution $x \Box \frac{b}{2a} \Box t$

6. Integration of type

Make the substitution $x + \frac{b}{2a}$, then split the integral as some of two integrals one containing the linear term and the other containing constant term.

7. Integration of trigonometric functions

OR $\frac{dx}{a \sin 2 \sqrt{b \sin x \cos x} \sqrt{a \cos 2 x}}$ put tan x = t.

OR
$$\frac{dx}{a \text{ MDSinxMccosx put tan}} \frac{x}{2} = t$$

8. Integration of type

$$\label{eq:constant} \boxed{ \begin{array}{c} x^2 \boxtimes 1 \\ x^4 \boxtimes Kx2 \boxtimes 1 \end{array}} \ dx \ \ \text{where K is any constant}.$$

Divide Nr & Dr by
$$x^2$$
 & put $x = \frac{1}{x} = t$.

Integration of type 9.

Integration of type 10.

$$\frac{dx}{(ax \Box b)\sqrt{px2 \Box qx \Box r}} \text{, put ax + b = } \frac{1}{t};$$

$$\frac{dx}{(ax2 \boxtimes b)\sqrt{px2 \square q}} , put x = \frac{1}{t}$$

DEFINITE INTEGRATION

Properties of definite integral

3.
$$\int_{a}^{b} f(x) dx = \int_{a}^{c} f(x) dx + \int_{c}^{b} f(x) dx$$

FUNDAMENTAL OF MATHEMATICS

Intervals:

Intervals are basically subsets of R and are commonly used in solving inequalities or in finding domains. If there are two numbers a, b \boxtimes R such that a < b, we can define four types of intervals as follows :

Symbols Used

- (i) Open interval : $(a, b) = \{x : a < x < b\}$ i.e. end points are not included.
- (ii) () or][Closed interval : [a, b] = {x : a ⊠ x ⊠ b} i.e. end points are also included.

This is possible only when both a and b are finite.

(iii) Open-closed interval : (a, b] = {x : a < x ⋈ b} (iv) (] or]]

Closed - open interval : [a, b) = x : a ⊠ x < b}
[) or [[

The infinite intervals are defined as follows:

- (i) $(a, \boxtimes) = \{x : x > a\}$ (ii) $[a, \boxtimes) = \{x : x \boxtimes a\}$
- (iii) $(-\boxtimes, b) = \{x : x < b\}$ $(\boxtimes, b] = \{x : x \boxtimes b\}$
- (v)' $(-\boxtimes\boxtimes\boxtimes) = \{x : x \boxtimes R\}$

Properties of Modulus:

For any a, b \square R |a| \boxtimes 0, |a| = |-a|, |a| \boxtimes a, |a| \boxtimes -a, |ab| = |a| |b|,

 $\left| \frac{a}{b} \right| = \frac{|a|}{|a|}, \quad |a+b| \boxtimes |a| + |b|, \quad |a-b| \boxtimes ||a| - |b||$

Trigonometrid Functions of Sum or Difference of Two Angles:

- (a) $|\sin(A \pm B)| = \sin A \cos B \pm \cos A \sin B$ $|\Delta 2 \sin A \cos B| = \sin(A+B) + \sin(A | B)$ and and $|\Delta 2 \cos A \sin B| = \sin(A+B) | |\Delta 3 \sin(A | B)$
- (b) $\cos (A \pm B) = \cos A \cos B \boxtimes \sin A \sin B$ $\boxtimes 2 \cos A \cos B = \cos (A+B) + \cos (A \boxtimes B)$ and $2 \sin A \sin B$ $= \cos (A \boxtimes B) \boxtimes \cos (A+B)$
- (c) $\sin^2 A \boxtimes \sin^2 B = \cos^2 B \boxtimes \cos^2 A = \sin (A+B)$. $\sin (A \boxtimes B)$
- (d) $\cos^2 A \boxtimes \sin^2 B = \cos^2 B \boxtimes \sin^2 A = \cos (A+B). \cos (A \boxtimes B)$
- (e) $\cot (A \pm B) = \frac{\cot A \cot B}{\cot B} \Box \cot A$
- $(f) \hspace{1cm} \tan (A+B+C) = \frac{tanA \boxtimes tanB}{1 \boxtimes tanAtanB} \hspace{0.2cm} \square \underset{tanB}{tanC} \square \underset{tanB}{tanC} \square \underset{tanB}{tanC} \square .$

3. Common Roots:

Consider two quadratic equations a

$$1 \% + b1 \times + c1 = 0 \& a2 \% + b2 \times + c2 = 0.$$

(i) If two quadratic equations have both roots common, then

$$\frac{a1}{a2} = \frac{b1}{b2} = \frac{c_1}{c_2}$$
.

(ii) If only one root \square is common, then

$$\Box = \frac{\text{c1}_{2} \Box \text{c2a1}}{\text{a}_{2} \Box \text{a2b}} = \frac{\text{b1}_{2} \Box \text{b2c}}{\text{c}_{2} \Box \text{1}}$$

$$\text{a1} \qquad 1 \qquad \text{c1} \qquad \text{c2a}$$

$$\text{b} \qquad \text{a} \qquad 1$$

4. Range of Quadratic Expression $f(x) = ax^2 + bx + c$.

Range in restricted domain: Given $x \square [x1, x2]$

(a) If $\Box \frac{b}{2a} \boxtimes [x1, x2]$ then,

$$\text{f(x)} \boxtimes \text{min}_{(x_1)} \boxtimes \text{f(x_2)} \square \text{max}_{(x_1)} \boxtimes \text{f(x_2)} \square$$

(b) If $\Box \frac{b}{2a} \boxtimes [x1, x2]$ then,

5. Location of Roots:

Let $f(x) = ax^2 + bx + c$, where $a > 0 & a, b, c <math>\boxtimes R$.

- (i) Conditions for both the roots of f(x) = 0 to be greater than a specified number'x' are $b^2 \boxtimes 4ac \boxtimes 0$; $f(x) > 0 \& (\boxtimes b/2a) > x0$.
- (ii) Conditions for both the roots of f(x) = 0 to be smaller than a specified number 'x'₀ are $b^2 \boxtimes 4ac \boxtimes 0$; $f(x = 0) > 0 \& (\boxtimes b/2a) < x0$.
- (iii) Conditions for both roots of f(x) = 0 to lie on either side of the number 'x0' (in other words the number 'x0' lies between the roots of f(x) = 0), is f(x) < 0.
- (iv) Conditions that both roots of f (x) = 0 to be confined between the numbers x_1 and x_2 , (x < x) are $b^2 \boxtimes 4$ ac $\boxtimes 0$; $f(x) > 0_1$; $f(x^2) > 0 \& x < (\boxtimes b/2a) < x^2$.
- (v) Conditions for exactly one root of f(x) = 0 to lie in the interval (x1, x2) i.e. x < x is f(x 1).f(x2) < 0.

SEQUENCE & SERIES

An arithmetic progression (A.P.): $a, a + d, a + 2 d, \dots a + (n \square 1) d$ is an A.F.

Let a be the first term and d be the common difference of an A.P., then nth term = t n = a + (n - 1) d

The sum of first n terms of A.P. are

$$\operatorname{Sn} = \frac{n}{2} [2a + (n-1) d] = \frac{n}{2} [a + \square \square]$$

rth term of an A.P. when sum of first r terms is given is t = Sr - Sr - 1.

Properties of A.P.

- (i) If a, b, c are in A.P. ⊠ 2 b = a + c & if a, b, c, d are in A.P. ⊠ a + d = b + c.
- (ii) Three numbers in A.P. can be taken as a \(\times \) d, a, a + d; four numbers in A.P. can be taken as a \(\times \) d, a + d, a + 3d; five numbers in A.P. are a \(\times \) 2d, a \(\times \) d, a, a + d, a + 2d & six terms in A.P. are a \(\times \) 5d, a \(\times \) 3d, a \(\times \) d, a + d, a + 3d, a + 5d etc.
- (iii) Sum of the terms of an A.P. equidistant from the beginning & end = sum of first & last term.

Arithmetic Mean (Mean or Average) (A.M.):

If three terms are in A.P. then the middle term is called the A.M. between the other two, so if a, b, c are in A.P., b is A.M. of a & c. n 🛮 Arithmetic Means Between Two Numbers:

An are the

n A.M.'s between a & b. A1 = $a + \frac{b \Box a}{c \Box 1}$,

$$A2 = a + \frac{2(b \Box a)}{n \Box 1} ,....., An = a + \frac{n(b\Box a)}{n \Box 1}$$

$$\prod_{r=1}^{n} Ar = nA \text{ where A is the single A.M. between a \& b.}$$

Geometric Progression:

a, ar, ar2, ar3, ar4,..... is a G.P. with a as the first term & r as common ratio.

nth term = a rn⊠1 (i)

(ii) Sum of the first n terms i.e. S n =
$$\boxed{r \boxtimes 1}$$
, $r \square 1$ \boxed{na} , $r \square 1$

(iii) Sum of an infinite G.P. when $\square r \square < 1$ is given by

$$SM = \frac{a}{1 \square r} \prod_{r} \Gamma \square 1 \square$$
.

Geometric Means (Mean Proportional) (G.M.):

If a, b, c > 0 are in G.P., b is the G.M. between a & c, then $b^2 = ac$ n⊠Geometric Means Between positive number a, b: If a, b are two given numbers & a, G_1G_{-2} ..., G_n , b are in G.P.. Then $G_1G_{-2}G_1$, G_2G_1 , G_3G_2 , G_3G_3, $G_nG_1G_2G_3$ between a & b.

$$G_1 = a(b/a)1/n+1$$
, $G_2 = a(b/a)2/n+1$,..., n ,= G_3

Harmonic Mean (H.M.):

If a, b, c are in H.P., b is the H.M. between a & c, then b = $\frac{2ac}{2^{Mc}}$.

H.M. H of a1, a2, an is given by
$$\frac{1}{H} = \frac{1}{n} = \frac{1}{a1} = \frac{1}{a2} = \frac{1}{a2} = \frac{1}{an}$$

Relation between means :

$$G^2 = AH$$
, A.M. \boxtimes G.M. \boxtimes H.M. (only for two numbers) and A.M. = G.M. = H.M. if a

Important Results

(iv)
$$\prod_{r=1}^{n} r = 1 + 2 + 3 + \dots + n = \frac{n (n \square 1)}{2}$$

BINOMIAL THEOREM

2. Properties of Binomial Theorem:

- (i) General term: T r+1 = Cr a-r br
- (ii) Middle term (s):
- (a) If n is even, there is only one middle term,

(b) If n is odd, there are two middle terms,

which are
$$\begin{bmatrix} n & 1 \\ 2 & \end{bmatrix}$$
 th and $\begin{bmatrix} n & 1 & 1 & 1 \\ 2 & \end{bmatrix}$ th terms.

3. Multinomial Theorem:

$$= \prod_{r1 \boxtimes r2 \boxtimes ... \boxtimes rk \boxtimes n} \frac{n!}{\mathfrak{f}! r_2! ... r_k!} \ xr11.x22.xrk$$

Here total number of terms in the expansion = $^{n+k-1}C_{k-1}$

Application of Binomial Theorem: 4.

If $(\sqrt{A} \boxtimes B) n = \boxtimes + f$ where \boxtimes and n are positive integers, n being odd and

If n is an even integer, then $(\boxtimes + f)(1 - f) = kn$

5. **Properties of Binomial Coefficients:**

(i)
$${}^{n}C0 + {}^{n}C1 + {}^{n}C2 + \dots + {}^{n}Cn = 2$$

(ii)
$${}^{n}C^{\underline{\alpha}} nC + nC - nC + nC - nC + (-1){}^{n}Cn = 0$$

(iii)
$${}^{n}C^{+} nC + {}_{2} nC + {}_{4} ... = nC + {}_{1} nC + {}_{1} nC + {}_{2} nC + ... = 2^{-1}$$

(iii)
$${}^{n}C^{+} nC + {}^{+} nC + {}^{+} = nC + {}^{+} nC + {}^{+} n C5 + = 2^{i-1}$$
(iv) ${}^{n}Cr + {}^{i}C {}_{r-1} = {}^{n+1}Cr(v) \frac{1}{n} = \frac{n \square r \square 1}{r}$

6. **Binomial Theorem For Negative Integer Or Fractional Indices**

$$(1 + x)n = 1 + nx + \frac{n(n \boxtimes 1)}{2!}x^2 + \frac{n(n \boxtimes 1)(n \square 2)}{3!}x^3 + \dots +$$

$$\frac{n(n\boxtimes 1)(r\boxtimes 2).....(n\boxtimes r\boxtimes 1)}{r!}xr+....,|x|<1.$$

$$T_{r+1} = \frac{n(n \boxtimes 1)(n \boxtimes 2).....(n \vdash r \vdash 1)}{r!} xr$$

PERMUTATION & COMBINNATION

1. Arrangement: number of permutations of n different things taken r at a

time =
$${}^{n}Pr = n (n \boxtimes 1) (n \boxtimes 2)... (n \boxtimes r + 1) = \frac{n!}{(n \square r)!}$$

2. Circular Permutation:

The number of circular permutations of n different things taken all at a time is; (n-1)!

3. Selection: Number of combinations of n different things taken r at a

time =
$$\mathbb{C}$$
 r = $\frac{n!}{r!(n \boxtimes r)!}$ = $\frac{{}^{n}P_{r}}{r!}$

4. The number of permutations of 'n' things, taken all at a time, when 'p' of them are similar & of one type, q of them are similar & of another type, 'r' of them are similar & of a third type & the remaining $n \boxtimes (p + q + r)$ are all

different is
$$\frac{n!}{p!q!r!}$$
.

5. Selection of one or more objects

(a) Number of ways in which atleast one object be selected out of 'n' distinct objects is

$${}^{n}C_{1} + nC_{2} + nC_{3} + \dots + nC_{n} = 2n - 1$$

(b) Number of ways in which atleast one object may be selected out of 'p' alike objects of one type 'q' alike objects of second type and 'r' alike of third type is

$$(p + 1) (q + 1) (r + 1) - 1$$

(c) Number of ways in which atleast one object may be selected from 'n' objects where 'p' alike of one type 'q' alike of second type and 'r' alike of third type and rest

$$n - (p + q + r)$$
 are different, is $(p + 1) (q + 1) (r + 1) 2n - (p + q + r) - 1$

6. Multinomial Theorem:

Coefficient of xr in expansion of $(1 \boxtimes x) \boxtimes n = n + r \boxtimes 1 (\mathfrak{T} \boxtimes N)$

- 7. Let N = pa. qb. rc..... where p, q, r..... are distinct primes & a, b, c.... are natural numbers then :
 - (a) The total numbers of divisors of N including 1 & N is = (a + 1) (b + 1) (c + 1)......

(b) The sum of these divisors is = (p0 + p1 + p2 + + pa) (q0 + q1 + q2 + + qb) (r0 + r1 + r2 + + rc).......

(c)	Number of ways in which N can be resolved as a product of two
	factors is

$$= \begin{array}{c} \frac{1}{2}(a\boxtimes 1)(b\boxtimes 1)(c\boxtimes 1).... & \text{if N isnot a perfect square} \\ \frac{1}{2}[(a\boxtimes 1)(b\boxtimes 1)(c\boxtimes 1)...] & \text{if Nis a perfect square} \end{array}$$

(d) Number of ways in which a composite number N can be resolved into two factors which are relatively prime (or coprime) to each other is equal to 2n⊠1 where n is the number of different prime factors in N.

8. Dearrangement:

Number of ways in which 'n' letters can be put in 'n' corresponding envelopes such that no letter goes to correct envelope is n

PROBABILITY

1. Classical (A priori) Definition of Probability:

If an experiment results in a total of (m + n) outcomes which are equally likely and mutually exclusive with one another and if 'm' outcomes are favorable to an event 'A' while 'n' are unfavorable, then the probability of

occurrence of the event 'A' = P(A) =
$$\frac{m}{m \boxtimes n} = \frac{n(A)}{n(S)}$$
.

We say that odds in favour of 'A' are m: n, while odds against 'A' are n: m.

$$P(\overline{A}) = \frac{n}{m \square n} = 1 - P(A)$$

2. Addition theorem of probability : $P(A \boxtimes B) = P(A) + P(B) - P(A \boxtimes B)$ De Morgan's Laws :

(a) $(A \boxtimes B)c = Ac \boxtimes Bc$ (b) $(A \square B)c = Ac \boxtimes Bc$

Distributive Laws:

(a) A
$$\square$$
 (B \boxtimes C) = (A \boxtimes B) \boxtimes (A \boxtimes C) (b) A \boxtimes (B \boxtimes C) = (A \boxtimes B) \boxtimes (A \boxtimes C)

(i)
$$P(A \text{ or } B \text{ or } C) = P(A) + P(B) + P(C) - P(A \boxtimes B) - P(B \boxtimes C) - P(C \boxtimes A) + P(A \boxtimes B \boxtimes C)$$

(ii) P (at least two of A, B, C occur) = P(B
$$\boxtimes$$
 C) + P(C \boxtimes A) + P(A \boxtimes B) – 2P(A \boxtimes B \boxtimes C)

(iii) P(exactly two of A, B, C occur) = P(B
$$\boxtimes$$
C) + P(C \boxtimes A) + P(A \boxtimes B) - 3P(A \boxtimes B \boxtimes C)

$$P(A) + P(B) + P(C) - 2P(B \square \square C) - 2P(C \square \square A) - 2P(A \square \square B) + 3P(A \square \square B \square \square C)$$

3. Conditional Probability :
$$P(A/B) = \frac{P(A \boxtimes B)}{P(B)}$$

4. Binomial Probability Theorem

If an experiment is such that the probability of success or failure does not change with trials, then the probability of getting exactly r success in n trials of an experiment is nC $p^r q^{n-r}$, where 'p' is the probability of a success and q is the probability of a failure. Note that p + q = 1.

5. Expectation:

If a value Mi is associated with a probability of pi , then the expectation is given by \boxtimes p iM.

Total Probability Theorem:
$$P(A)^n = \boxtimes P(Bi) . P(A/Bi)$$

Bayes' Theorem :

If an event A can occur with one of the n mutually exclusive and exhaustive events B1, B2,, Bn and the probabilities P(A/B1), P(A/B2) P(A/Bn) are

known, then
$$P(Bi/A) = \frac{P(Bi).P(A/Bi)}{\sum_{i=1}^{n} P(Bi).P(A/Bi)} B1, B2, B3,...,Bn$$

$$\mathsf{A} = (\mathsf{A} \boxtimes \mathsf{B} \ \mathsf{1}) \boxtimes (\mathsf{A} \boxtimes \mathsf{B2}) \ _{\square} \ (\mathsf{A} \boxtimes \mathsf{B} \ \mathsf{3}) \boxtimes \ldots \ldots \boxtimes (\mathsf{A} \boxtimes \mathsf{Bn})$$

$$P(A) = P(A \boxtimes B)_{1} + P(A \square B_{2}) + \dots + P(A \boxtimes B_{n}) = \boxtimes$$

8. Binomial Probability Distribution:

(i) Mean of any probability distribution of a random variable is given by :

$$\mu = \frac{\boxtimes p_{ixi} = \boxtimes p_{x} = np}{\boxtimes p_{i}}$$

n = number of trials

p = probability of success in each probability

q = probability of failure

(ii) Variance of a random variable is given by,

$$\boxtimes 2 = \boxtimes \boxtimes (x_i - \mu)2$$
. $p = \boxtimes \boxtimes p_i x_i^2 - \mu^2 = npq$

COMPLEX NUMBER

1. The complex number system

z = a + ib, then a - ib is called congugate of z and is denoted by $\frac{1}{2}$

Equality In Complex Number:

$$z_1 = z_2$$
 $\square \square \square \square \square \mathbb{R}e(z) = \mathbb{R}e(z^2)$ and $\mathbb{R}e(z^1) = \mathbb{R}e(z^2)$.

3. Properties of arguments

- arg(z172)=arg(z1)+arg(z2)+2md9689meinteggem.(i)
- (ii)
- arg(z2) = 2arg(z) + 2mfor some integer m. (iii)

П

-) arg(z) = 0П $arg(z) = \pm \boxtimes /2$
- z is a positive real number z is purely imaginary and z

 ∅ 0

4. Properties of conjugate

(v)

(iv

- (i)
- $|z| = |\overline{z}|$ (ii) $z\overline{z} = |z|2(iii)$ $\overline{z_1 \Box z_2} = \overline{z}_1 + \overline{z}_2$

(iv)
$$\overline{z_1 \Box z_2} = \overline{z}_1 - \overline{z}_2$$

$$(v) \qquad \overline{z} \ \overline{z}_2 = \overline{z} 1 \overline{z} 2$$

(iv)
$$\overline{z_1} \Box z\overline{2} = \overline{z}_1 - \overline{z}_2$$
 (v) $\overline{z} \ \overline{z}_2 = \overline{z}1\overline{z}2$
(vi) $\overline{z}_1 \Box z\overline{2} = \overline{z}_1 \overline{z}2$ $z_2 = \overline{z}1\overline{z}2$

(vii)
$$|z^{1+} z^{2}|^{2} = (z^{1} + z^{2})(\overline{z^{1} \Box z_{2}}) = |z^{1}|^{2} + |z^{2}|^{2} + z^{1}\overline{z}^{2} + \overline{z}^{1}z^{2}$$

(viii)
$$\overline{(\overline{z}1)} = z$$

(ix) If
$$w = f(z)$$
, then $\overline{w} = f(\overline{z})$

(x)
$$arg(z) + arg(\overline{z})$$

5. Rotation theorem

If P(z1), Q(z2) and R(z3) are three complex numbers and \square PQR = \square then

$$\begin{vmatrix} z_3 & \Box z_2 \\ z_1 & \Box z_2 \end{vmatrix} = \begin{vmatrix} z_3 & \Box z_2 \\ z_1 & \Box z_2 \end{vmatrix} ei^{\Box}$$

6. Demoivre's Theorem:

If n is any integer then

(i)
$$(\cos \square + i \sin \square) n = \cos n\square + i \sin n\square$$

(ii)
$$(\cos \boxtimes 1 + i \sin \boxtimes 1) (\cos \boxtimes 2 + i \sin \boxtimes 2) (\cos \square_3 + i \sin \square_2)$$

 $(\cos \boxtimes 3 + i \sin \boxtimes 3) \dots (\cos \boxtimes n + i \sin \boxtimes n) = \cos (\boxtimes 1 + \boxtimes 2 + \dots \square_n) + i \sin (\boxtimes 1 + \boxtimes 2 + \boxtimes 3 + \dots + \boxtimes n)$

7. Cube Root Of Unity:

- (i) The cube roots of unity are 1, $\frac{\Box 1 \Box i \sqrt{3}}{2}$, $\frac{\Box 1 \Box i \sqrt{3}}{2}$.
- (ii) If \boxtimes is one of the imaginary cube roots of unity then $1 + \boxtimes + \boxtimes^2 = 0$. In general $1 + \boxtimes r + \boxtimes 2r = 0$; where $r \boxtimes l$ but is not the multiple of 3.

8. Geometrical Properties: 1 – z2|.

Distance formula : |z

Section formula :
$$z = \frac{mz_2 \boxtimes nz}{m \boxtimes n}$$
 (internal division), $z = \frac{mz_2 \boxtimes nz}{m \boxtimes n}$ (external

division)

- (1) $amp(z) = \mathbb{N}$ is a ray emanating from the origin inclined at an angle \mathbb{N} to the $x\mathbb{N}$ axis.
- (2) $\boxtimes z \boxtimes a \boxtimes = \boxtimes z \boxtimes b \boxtimes$ is the perpendicular bisector of the line joining a to b.

(3) If
$$\left| \frac{z \square z_1}{z \square z_2} \right| = k \square 1$$
, 0, then locus of z is circle.

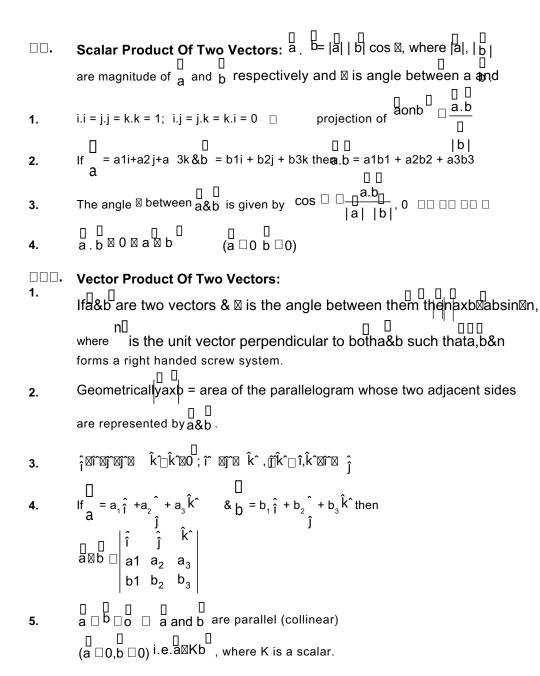
VECTORS

☐ Position Vector Of A Point:

let O be a fixed origin, then the position vector of a point P is the vector \overrightarrow{OP} . If a and b are position vectors of two points A and B, then, $\overrightarrow{AB} = \overrightarrow{DMa} = \overrightarrow{PV}$ of B \boxtimes pv of A.

DISTANCE FORMULA: Distance between the two points A(a) and B(b)

is
$$AB = \begin{bmatrix} \begin{bmatrix} 1 & 1 \\ a & b \end{bmatrix} \end{bmatrix}$$



6.	Unit vector perpendicular to the plane of $a\&bis\hat{n}$ \Box $a\times b$ $a\times b$
. .	
	☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
	ABC = 1 DE XCECXAE.
	The points A, B & C are collinear if axb\(\text{\mathbb{M}}\)bxc\(\text{\mathbb{M}}\) \(\text{\mathbb{C}} \text{\mathbb{A}} \)
	Area of any quadrilateral whose diagonal vectors are $d1 \& d2$ is given by $\frac{1}{2} \begin{vmatrix} 1 & 0 \\ 1 & 2 \end{vmatrix}$
	Lagrange's Identity: (axb)2\(\text{a} \big \big \text{\big } \(\text{a} \big \big \text{\big } \(\text{a} \big \big \text{\big } \(\text{a} \big \big \big \\ \text{\big } \(\text{a} \big \big \big \\ \text{\big } \(\text{a} \big \big \\ \text{\big } \(\text{a} \big \big \big \\ \text{\big } \(\text{a} \big \big \big \\ \text{\big } \(\text{a} \big \big \\ \text{\big } \(\text{a} \big \big \\ \text{\big } \(\text{\big } \\ \t
⊠V.	Scalar Triple Product: The scalar triple product of three vectors ₩,b&c⊠ is defined as
	□ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □
	U ∐ ∐ Volume of tetrahydron V⊠[abc] In a scalar triple product the position of dot & cross can be interchanged
	i.e. □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □ □
	$ \begin{bmatrix} & & & & & & & \\ & & & & & & \\ & & & &$
	☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
	Volume of tetrahedron OABC with O as origin & A(ab) and C(c) be the vertices = 1 [a b c]

	The positon vector of the centroid of a tetrahedron if the pv's of its vertices \[\begin{array}{cccccccccccccccccccccccccccccccccccc
V.	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
	3-DIMENSION
1.	Vector representation of a point :
2.	Position vector of point P (x, y, z) is $x \hat{j} + y \hat{j} + z \hat{k}$. Distance formula:
	$\sqrt{(x1\Box x_2)^2\Box (y1\Box y_2)^2\Box (z1\Box z_2)^2}\;,\qquad AB = \overrightarrow{OB}-\overrightarrow{OA} $
3.	Distance of P from coordinate axes :
	$PA = \sqrt{y^2 \square z^2}$, $PB = \sqrt{z^2 \square x^2}$, $PC = \sqrt{x^2 \square y^2}$
4.	
	Mid point: $x \square \frac{x1 \boxtimes x2}{2}, y \boxtimes \frac{y1 \boxtimes y}{2}, z \square \frac{z_1 \square z2}{2}$
5.	Direction Cosines And Direction Ratios (i) Direction cosines: Let ⋈⋈⋈⋈⋈ be the angles which a directed line makes with the positive directions of the axes of x, y and z respectively, then cos ⋈, cos⋈⋈ cos ⋈ are called the direction cosines of the line. The direction cosines are usually denoted by (⋈, m, n). Thus ⋈ij = cos ⋈, m, n, n estive the directions of a line, then ⋈2 + m2 + n2 = 1 (iii) Direction ratios: Let a, b, c be proportional to the direction cosines ⋈, m, n then a, b, c are called the direction ratios. (iv) If ⋈, m, n be the direction cosines and a, b, c be the direction ratios of a vector, then
	$\begin{array}{c ccccccccccccccccccccccccccccccccccc$

(vi) If the coordinates P and Q are
$$(x_1, y_1, z_1)$$
 and (x_2, y_2, z_2) then the direction ratios of line PQ are, $a = x$

the direction cosines of
$$\quad \text{line PQ are} \quad \stackrel{\boxtimes \boxtimes}{=} \frac{\underline{x} \; 2 \square \; \; x_1}{\mid \; P \; \; Q \; \mid}$$

$$m = \frac{y2 \square y1}{|PO|}$$
 and $n = \frac{z2 \square z1}{|PO|}$

6. Angle Between Two Line Segments:

The line will be perpendicular if a1a2 + b1b2 + c1c2 = 0,

parallel if
$$\frac{a_1}{a_2} = \frac{b}{1} = \frac{c}{1}$$

7. Projection of a line segment on a line

If P(x1, y1, z1) and Q(x2, y2, z_2^2) then the projection of PQ on a line having direction cosines \boxtimes , m, n is

$$| \square(x_2 \square_{x1}) \square m(y_2 \square_{y1}) \square n(z2 \square_{z1}) |$$

- **8.** Equation Of A Plane: General form: ax + by + cz + d = 0, where a, b, c are not all zero, a, b, c, $\mathbb{Z}d\mathbb{R}$.
 - (i) Normal form : $\boxtimes x + my + nz = p$
 - Plane through the point $(x_1, y_1) = 0$ $a(x \boxtimes x) + b(y \boxtimes y_1) + c(z \boxtimes z_1) = 0$
 - (i ii) Intercept Form: $\frac{x}{a} \Box \frac{y}{b} \Box \frac{z}{c} \Box 1$ Vector form: $(r \boxtimes a) . n \boxtimes = 0$ or $r \cap a = a$. $n \boxtimes a \cap b$
 - (iv)
 - (v) Any plane parallel to the given plane ax + by + cz + d = 0 is ax + by + cz + a = 0. Distance between $ax + by + c\frac{1}{2} = 0$

ax + by + cz + d₂= 0 is =
$$\frac{|d_1 \boxtimes d_2|}{\sqrt{a^2 \Box b^2 \Box c^2}}$$

(vi) Equation of a plane passing through a given point & parallel to the given vectors:

9. A Plane & A Point

(i) Distance of the point $(x \boxtimes, y \boxtimes, z \boxtimes)$ from the plane ax + by + cz+ d = 0

given by
$$\frac{ax' \square by' \square cz' \square d}{\sqrt{a2\square b2\square c2}}.$$

(ii) Length of the perpendicular from a point (a) to plane r.n = d

is given by
$$p = \frac{|a| n |d|}{|a|}$$
.

(i ii) Foot (xx, yx, xx) of perpendicular drawn from the point (x) to

the plane ax + by + cz + d = 0 is given by
$$\frac{x' \Box x_1}{a} \Box \frac{y' \Box y_1}{b} \boxtimes \frac{z' \Box z_1}{c}$$

$$= - \frac{(ax1 \boxtimes by_1 \square_{CZ_1} \square_d)}{a2 \boxtimes b^2 \square_C^2}$$

(iv) To find image of a point w.r.t. a plane:

Let P (x1, y1, z1) is a given point and ax + by + cz + d = 0 is given plane Let $(x \ y, y \ z)$ is the image point. then

$$\frac{x'\boxtimes x1}{a}\square\frac{y'\boxtimes y1}{b}\square\frac{z'\boxtimes z1}{c}=-2\frac{(ax1\boxtimes by_1\square_{CZ_1}\square_d)}{a2\boxtimes b^2\square_{C^2}}$$

10. Angle Between Two Planes:

$$\cos \Box = \left| \frac{\text{aa' } \boxtimes \text{bb'} \boxtimes \text{cc'}}{\sqrt{\text{a}^2 \boxtimes \text{b2} \boxtimes \text{c2}/\text{a'2} \boxtimes \text{b'} \Box_{\text{c'}}^2}} \right|$$

Planes are perpendicular if aa⊠ + bb⊠ + cc⊠ = 0 and planes are parallel

$$\frac{a}{a'} = \frac{b}{b'} = \frac{c}{c'}$$

$$\Box = \frac{\begin{array}{c} \square & \square \\ -\square & \square & \square \\ |n1|.|n \square & | \end{array}}{|n1|.|n \square & |}$$

n \square \square Planes are perpendicular if 1.n2 = 0 & planes are parallel if

11. Angle Bisectors

(i) The equations of the planes bisecting the angle between two given planes

$$a1x + b1y + c1z + d1 = 0$$
 and $a2x + b2y + c2z + d2 = 0$ are

$$\frac{a_1^{\times} \boxtimes b1y \boxtimes c1z \boxtimes d}{\sqrt{a_1^{\times} \boxtimes b2^{\times}_1}} \ \ = \pm \ \frac{a_2^{\times} \boxtimes b2y \ \boxtimes \ c2 \boxtimes d2}{\sqrt{a22 \boxtimes b22 \underset{2}{\boxtimes}} c}$$

(ii) Bisector of acute/obtuse angle: First make both the constant terms positive. Then

12. Family of Planes

(i) Any plane through the intersection of a1x + b1y + c1z + d1 = 0 & a2x + b2y + c2z + d2 = 0 & (a2x + b2y + c2z + d2) = 0 a

The equation of plane passing through the intersection of the planes r.n = d1 & r . $n^2 = d2$ isr. $(n^2 + m^2) = d1$ where $m = d^2 + d^2 = d$

13. Volume Of A Tetrahedron: Volume of a tetrahedron with vertices A (x1, y1, z1), B(x2, y2, z2), C (x3, y3, z3) and

$$\text{D (x4, y4, z4) is given by V} \underbrace{\frac{1}{6}} \begin{bmatrix} x_1 & y_1 & z_1 & 1 \\ x_2 & y_2 & z_2 & 1 \\ x_3 & y_3 & z_3 & 1 \\ x_4 & y_4 & z_4 & 1 \end{bmatrix}$$

A LINE

1. **Equation Of A Line**

- (i) A straight line is intersection of two planes. it is represented by two planes a1x + b1y + c1z + d1 = 0 and a2x + b2y + +c2z + d2 = 0.
- Symmetric form : $\frac{x \coprod x_1}{a} = \frac{y \coprod y \bot}{n} = \frac{z \coprod z_1}{c} = r$. (ii)
- (iii)
- (iv) Reduction of cartesion form of equation of a line to vector form & vice

$$\frac{X \square X_1}{a} = \frac{y \square y_1}{b} = \frac{z \square z_1}{c} \boxtimes r = (x^{\hat{}}_1 \hat{i} + y \hat{j}_1 + z \hat{k}_1) + \boxtimes (a\hat{i} + b\hat{j} + c \hat{k}_1).$$

2. Angle Between A Plane And A Line:

If \boxtimes is the angle between $\lim_{n \to \infty} \frac{y \cdot y \cdot 1}{n} = \frac{y \cdot y \cdot 1}{n} = \frac{z \cdot z \cdot 1}{n}$ and the plane ax + by + cz + d = 0, then (i)

$$\sin \square = \left| \frac{a \boxtimes \square_{bm} \square_{cn}}{\sqrt{\left(a^2 \boxtimes b2 \square_{c2}\right)}\sqrt{\square^2 \square_{m2} \square_{n^2}}} \right|.$$

- Vector form: If \mathbb{R} the angle between a line $r = (a + \Box h)$ and (ii)
 - $r \cdot n = d$ then $\sin \Box \Box \Box b \cdot n \Box \Box$.
- Condition for perpendicularity $\frac{\Box}{a} = \frac{m}{b} = \frac{n}{c}$, $\frac{\Box}{b} \times n = 0$ $\frac{\Box}{b} \times n = 0$ (iii)
- (iv)

3. Condition For A Line To Lie In A Plane

- Cartesian form: Line $\frac{x \square x_1}{\square} = \frac{y \square y^1}{m} = \frac{z \square z_1}{n}$ would lie in a plane ax + by + cz + d = 0, if ax = 1 + by + cz + d = 0 & (i) a⊠ + bm + cn = 0. _
- Vector form: Liner (ii) ☐ n☐ ☐ n☐ = d if b = 0 & = d

4. Skew Lines:

The straight lines which are not parallel and non\(\mathbb{\text{Coplanar}}\) i.e. (i) non⊠intersecting are called skew lines.

lines
$$\frac{x-\Box}{\Box} \Box \frac{y-\Box}{m} \Box \frac{z-\boxtimes}{n} \& \frac{x-\boxtimes'}{\boxtimes'} \Box \frac{y-\Box'}{m'} \Box \frac{z-\boxtimes'}{n'}$$

If
$$\Box = \begin{bmatrix} \Box & \Box & \Box & \Box & \Box & \Box \\ & m & n & \Box & 0 \end{bmatrix}$$
, then lines are skew.

(ii) Shortest distance formula for lines

Vector Form: For lines r = a1 + Mp and $r = a_2 + \Box b_2$ to be skew (i ii)

(v) Condition of coplanarity of two lines
$$r = a + \Box b \& r = c + \Box d$$
 is $[a-c b d] \Box 0$

5. Sphere

General equation of a sphere is x2 + y2 + z2 + 2ux + 2vy + 2wz + d = 0.

 $(\boxtimes u, -v, \boxtimes w)$ is the centre and $u_2\boxtimes v_2\boxtimes w_2\boxtimes d$ is the radius of the sphere.

6. Area of Triangle (

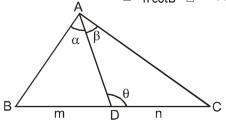
$$\Box = \frac{1}{2} ab \ sin \ C = \frac{1}{2} bc \ sin \ A = \frac{1}{2} ca \ sin \ B = \sqrt{s(s \Box a)(s \Box b)(s \Box c)}$$

7. m - n Rule:

If BD : DC = m : n, then

$$(m+n) \cot \boxtimes \square \quad mcot \ \square \ \square \ n \ cot \square$$

 \square n cotB \square m cotC



8. Radius of Circumcirlce:

$$R = \frac{a}{2 \sin A} \Box \frac{b}{2 \sin B} \Box \frac{c}{2 \sin C} = \frac{abc}{4 \Box}$$

9. Radius of The Incircle:

(i)
$$r = \frac{\Box}{s}$$

(ii)
$$r = (s^{\boxtimes} a) \tan \frac{A}{2} = (s^{\boxtimes} b) \tan \frac{B}{2} = (s^{\boxtimes} c) \tan \frac{C}{2}$$

(iii)
$$r = 4R \sin \frac{A}{2} \sin \frac{B}{2} \sin \frac{C}{2}$$

10. Radius of The Ex- Circles:

(i) r1 =
$$\frac{\Box}{s \Box a}$$
 : r2 = $\frac{\Box}{s \Box b}$: r3 = $\frac{\Box}{s \Box c}$

(ii)
$$r1 = s \tan \frac{A}{2}$$
: $r2 = s \tan \frac{B}{2}$: $r3 = s \tan \frac{C}{2}$

(iii) r1 = 4 R
$$\sin \frac{A}{2}$$
. $\cos \frac{B}{2}$. $\cos \frac{C}{2}$

SOLUTION OF TRIANGLE

1 Sine Rule:
$$\frac{a}{\sin A} \Box \frac{b}{\sin B} \Box \frac{c}{\sin C}$$
.

. Cosine Formula:

(i)
$$\cos A = \frac{b^2 \left[c \right] \left[a2 \right]}{2bc}$$
 (ii) $\cos B = \frac{c^2 \left[a2 \right] \left[b^2 \right]}{2ca}$
(iii) $\cos C = \frac{a2 \left[b2 \right] \left[c^2 \right]}{2ab}$

3. Projection Formula:

4. Napier's Analogy - tangent rule:

(i)
$$\tan \frac{B \boxtimes C}{2} = \frac{b \square c}{b \square c} \cot \frac{A}{2}$$
 (ii) $\tan \frac{C \boxtimes A}{2} = \frac{c \square a}{c \square a} \cot \frac{B}{2}$

(iii) tan
$$\frac{A \square B}{2} = \frac{a \square b}{a \square b} \cot \frac{C}{2}$$

5. Trigonometric Functions of Half Angles:

(i)
$$\sin \frac{A}{2} = \sqrt{\frac{(s \Box b)(s \Box c)}{bc}} ; \sin \frac{B}{2} = \sqrt{\frac{(s \Box c)(s \Box a)}{ca}} ;$$
$$\sin \frac{C}{2} = \sqrt{\frac{(s \Box a)(s \Box b)}{a b}}$$

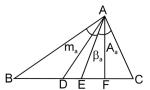
(ii)
$$\cos \frac{A}{2} = \sqrt{\frac{s (s \square a)}{bc}} ; \cos \frac{B}{2} = \sqrt{\frac{s (s \square b)}{ca}} ; \cos \frac{C}{2} = \sqrt{\frac{s (s \square c)}{ab}}$$

(i ii)
$$\tan \frac{A}{2} = \sqrt{\frac{(s \Box b)(s \Box c)}{s(s \Box a)}} = \frac{\Box}{s(s \Box a)}$$
 where $s = \frac{a \Box b \Box c}{2}$ is semi perimetre of triangle.

(iv)
$$\sin A = \frac{2}{bc} \sqrt{s(s \square a)(s \square b)(s \square c)} = \frac{2\square}{bc}$$

11. Length of Angle Bisectors, Medians & Altitudes :

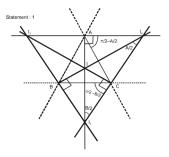
(i) Length of an angle bisector from the angle $A = \mathbb{Z}$ $a = \frac{2 bc \cos \frac{A}{2}}{b \Box c}$



- (ii) Length of median from the angle A = ma = $\frac{1}{2} \sqrt{2b2 \square 2c2 \square a^2}$
- & (iii) Length of altitude from the angle A = A a = $\frac{2[]}{a}$

12. Orthocentre and Pedal Triangle:

The triangle KLM which is formed by joining the feet of the altitudes is called the Pedal Triangle.



- (i) Its angles are ⋈⋈⋈ 2A, ⋈⋈⋈ 2B and ⋈⋈⋈ 2C.
- (ii) Its sides are a cosA = R sin 2A,

(iii) Circumradii of the triangles PBC, PCA, PAB and ABC are equal.

- **Excentral Triangle:** The triangle formed by joining the three excentres $\[Mathbb{M}\]$ 1, $\[Mathbb{M}\]$ 2 of $\[Mathbb{M}\]$ of $\[Mathbb{M}\]$ 3 of $\[Mathbb{M}\]$ 4 of $\[Mathbb{M}\]$ 5 of $\[Mathbb{M}\]$ 13.
 - △ ABC is the pedal triangle of the △ △ 1 △ 2 △ 3. (i)
 - Its angles are $\frac{\Box}{2} \Box \frac{A}{2}$, $\frac{\Box}{2} \Box \frac{B}{2} & \frac{\Box}{2} \Box \frac{C}{2}$. (ii)
 - Its sides are 4 R $\cos \frac{A}{2}$, 4 R $\cos \frac{B}{2}$ & 4 R $\cos \frac{C}{2}$. (iii)
 - $\begin{array}{l} \text{MMM} = 4_{R} \sin \frac{A}{2} \; ; \; \text{MMM2} = 4 \; R \sin \frac{B}{2} \; ; \; \text{MMM3} = 4 \; R \sin \frac{C}{2} \; . \\ \text{Incentre } \text{M} \text{ of } \text{M} \text{ ABC is the orthocentre of the excentral } \quad \square \; \text{ and } \text{ of } \text{M} \text{ of } \text{M} \text{ of } \text{M} \text{ of } \text{M} \text{ of } \text{ of } \text{M} \text{ of } \text{ o$ (iv)

(v)

- 14. **Distance Between Special Points:**
 - (i) Distance between circumcentre and orthocentre $OH2 = R2 (1 - 8 \cos A \cos B \cos C)$
 - (ii) Distance between circumcentre and incentre

$$OM2 = R2(1 - 8 \sin \frac{A}{2} \frac{\sin B}{2} \sin \frac{C}{2}) = R2 - 2Rr$$

(iii) Distance between circumcentre and centroid

$$OG2 = R2 - \frac{1}{9}(a2 + b2 + c2)$$

INVERSE TRIGONOMETRIC FUNCTIONS

1. Principal Values & Domains of Inverse Trigonometric/Circular Functions:

	Function	Domain	Range
(i)	y = sin⊠1 x where	⊠1⊠x □1	$\square \stackrel{\square}{=} \square_y \square \stackrel{\square}{=}$
(ii)	y = cos⊠1 x where	$\boxtimes 1 \boxtimes x \square 1$	0 □y □ □
(iii)	y = tan⊠1 x where	x⊠R	[⊔]
(iv)	y = cosec⊠ x where	x □ □1 or x □ 1	$\Box_{\frac{1}{2}} \Box_{y} \Box_{\frac{1}{2}}, y \Box_{0}$
(v)	y = sec⊠1 x where	$_{X}$ \square \square or $_{X}$ \boxtimes $_{1}$	0 ⋈ y □ □ y □ □ 2
(vi)	y = cot⊠1 x where	$x \squareR$	0 < y < □

STATISTICS

1. Arithmetic Mean / or Mean

If x1, x2, x3,.....xn are n values of variate xi then their A.N.s. defined as

$$\overline{x} = \frac{x^{1 \boxtimes x} \quad 2 \boxtimes 3 \boxtimes \quad \dots \boxtimes xn}{x} = i \underbrace{\boxtimes^{1} i_{x}}_{n}$$

If x1, x2, x3, xn are values of veriate with frequencies f1, f2, f3,......fn ther their A.M. is given by

$$_{\overline{x}} \ = \ \frac{\mathsf{f}_{1}\mathsf{x}_{1} \ \Box \mathsf{f}_{2}\mathsf{x}_{2} \ \Box \mathsf{f} \mathsf{3} \mathsf{x} \mathsf{3} \ \boxtimes \ldots \ldots \mathsf{f}_{n} \ \mathsf{f}_{n}}{\mathsf{f}_{1} \ \Box \mathsf{f}_{2} \ \Box \mathsf{f} \mathsf{3} \ \Box \ldots \ldots \boxtimes \ \mathsf{f}_{n}} \ = \ \underline{\overset{n}{\boxtimes} \mathsf{f}} \mathbf{i} \mathsf{x} \ \mathsf{i} \\ \underline{\overset{n}{\boxtimes} \mathsf{1}} \ , \ \text{where} \ \mathsf{N} \ = \ \underline{\overset{n}{\boxtimes} \mathsf{f}} \mathbf{i}$$

2. Properties of Arithmetic Mean:

- (i) Sum of deviation of variate from their A.M. is always zero that is $\neg \exists x = 0$.
- (ii) Sum of square of deviation of variate from their A.M. is minimum that is 🖾🗴 is minimum
- (iii) If \overline{x} is mean of variate xi then A.M. of $(x^i + \boxtimes) = x + \boxtimes$ A.M. of \boxtimes i . xi = \boxtimes .x A.M. of $(ax^i + b) = ax + b$

3. Me di an

The median of a series is values of middle term of series when the values are written is ascending order or descending order. Therefore median, divide on arranged series in two equal parts

For ungrouped distribution: If n be number of variates in a series then

4. Mode

If a frequency distribution the mode is the value of that variate which have the maximum frequency. Mode for

For ungrouped distribution:

The value of variate which has maximum frequency.

For ungrouped frequency distribution:

The value of that variate which have maximum frequency. Relationship between mean, median and mode.

- (i) In symmetric distribution, mean = mode = median
- (ii) In skew (moderately asymmetrical) distribution, median divides mean and mode internally in 1 : 2 ratio.

5. Range

$$\frac{\text{differenceofextremevalues}}{\text{sumofextremevalues}} = \frac{L \boxtimes}{S}$$

where L = largest value and S = $\frac{L}{S}$ Mallest value

6. Mean deviation :

$$\text{Mean deviation} = \frac{\prod_{i \boxtimes 1}^{n} |x_i| \boxtimes A|}{\prod_{i \boxtimes 1}^{n} |x_i|}$$

Mean deviation =
$$\frac{\prod_{i \ge 1}^{n} fi \mid xi^{\boxtimes} A \mid}{\prod_{i \ge 1} N}$$
 (for frequency distribution)

7. Variance:

Standard deviation = \sqrt{v} ar iance formula

$$\Box_{x}^{2} = \frac{\Box_{x} \Box i_{\overline{x}} \Box}{n} \Box 2$$

$$\Box_{x}^{2} = \frac{\overset{\square}{\square} X_{i}^{2}}{n} - \overset{\square}{\square} \overset{\square}{\square} = \overset{\square}{\square} X_{i}^{2} - \overset{\square}{\square} Z$$

$$\Box_{_{\!d}}^{\,2} = \frac{\boxtimes d_{_{\!\!1}}^2}{n} - \frac{\Box \ \Box di_{_{\!\!1}}^2\Box}{\Box \ n} \,, \text{ where di} = xi - a \;, \text{ where } a = assumed mean}$$

(ii) coefficient of S.D. =
$$\overline{x}$$
 \Box coefficient of variation = \overline{x} \Box × 100 (in percentage)

Properties of variance :

- (i) var(xi + ⋈) = var(xi) (ii) var(⋈.xi) = ⋈(var xi)
- (iii) $var(a x_i + b) = \hat{a}(var x_i)$ where \(\mathbb{A} \), a, b are constant.

MATHEMATICAL REASONING

Let p and q are statements

р	q I	o⊠q p	vq p	⊠q	q⊠p	p⊠q	q⊠p	
Т	Т	Т	Т	Т	Т	T	T	
Т	F	F	Т	F	Т	F	F	
F	Т	F	F	Т	F	F	F	
F	F	F	F	Т	T	Т	Т	

Tautology: This is a statement which is true for all truth values of its components. It is denoted by t.

Consider truth table of p v ~ p

р	~p	pv∼p
Т	F	Т
F	Т	Т

Fallacy: This is statement which is false for all truth values of its components. It is denoted by f or c. Consider truth table of $p^{^{\sim}}$ p

р	~p	р⊠∼р
Т	F	F
F	Т	F

(i) Statements		p⊠q p□q		p⊠q		р⊠	q
	Negation	(~p)⊠(~c	ı) (~p)□(~q)	p ⊠ ((~q) p 🛭	-q

Let p ⋈ qThen

(ii) Contrapositive of p⋈ q)is(~q □ ~p)

SETS AND RELATION

Laws of Algebra of sets (Properties of sets):

- (i) Commutative law : (A ⋈ B) = B ⋈ A′; A ⋈ B = B ⋈ A
- (ii) Associative law($A \boxtimes B$) $\boxtimes C = A \boxtimes (B \boxtimes C)$; $(A \boxtimes B) \boxtimes C = A \boxtimes (B \boxtimes C)$
- (iii) Distributive law:

 $\overrightarrow{A} \boxtimes (B \boxtimes C) = (A \boxtimes B) \boxtimes (A \boxtimes C) ; A \boxtimes (B \boxtimes C) = (A \boxtimes B) \boxtimes (A \boxtimes C)$

- (iv) De-morgan law : $(A \boxtimes B)' = A' \boxtimes B'$; $(A \boxtimes B)' = A' \boxtimes B'$
- (v) Identity law : $A \boxtimes U = A$; $A \boxtimes \boxtimes = A$
- (vi) Complement law : $A \boxtimes A' = U$, $A \boxtimes A' = \boxtimes$, (A')' = A
- (vii) Idempotent law : $A \boxtimes A = A$, $A \boxtimes A = A$

Some important results on number of elements in sets :

If A, B, C are finite sets and U be the finite universal set then

(i)
$$n(A \boxtimes B) = n(A) + n(B) - n(A \boxtimes B)$$

- (ii) $n(A B) = n(A) n(A \boxtimes B)$
- (iii) $n(A \boxtimes B \boxtimes C) = n(A) + n(B) + n(C) n(A \boxtimes B) n(B \boxtimes C) n$ $(A \boxtimes C) + n(A \boxtimes B \boxtimes C)$
- (iv) Number of elements in exactly two of the sets A, B, C = $n(A \boxtimes B) + n(B \boxtimes C) + n(C \boxtimes A) - 3n(A \boxtimes B \boxtimes C)$
- (v) Number of elements in exactly one of the sets A, B, C = $n(A) + n(B) + n(C) - 2n(A \boxtimes B) - 2n(B \boxtimes C) - 2n(A \boxtimes C) + 3n(A \boxtimes B \boxtimes C)$

Types of relations:

In this section we intend to define various types of relations on a given set A.

- (i) **Void relation**: Let A be a set. Then $\boxtimes A \times A$ and so it is a relation A. This relation is called the void or empty relation on A.
- (ii) Universal relation: Let A be a set. Then $A \times A \boxtimes A \times A$ and so it is a relation on A. This relation is called the universal relation on A.
- (iii) Identity relation: Let A be a set. Then the relation $A = \{(a, a) : a \boxtimes a \subseteq a\}$
- A) on A is called the identity Felation on A is called the identity relation on A is called the identity relation on A is called the identity is related to itself only.
- (iv) Reflexive relation: A relation R on a set A is said to be reflexive if every element of A is related to itself. Thus, R on a set A is not reflexive if there exists an element $a \boxtimes A$ such that $(a, a) \boxtimes R$.

Note: Every identity relation is reflexive but every reflexive relation in not identity.

- (v) Symmetric relation: A relation R on a set A is said to be a symmetric relation iff $(a, b) \boxtimes R \boxtimes (b, a) \boxtimes R$ for all $a, b \boxtimes A$. i.e. $a R b \boxtimes b R a$ for all $a, b \boxtimes A$.
- (vi) Transitive relation: Let A be any set. A relation R on A is said to be a transitive relation iff (a, b) \boxtimes R and (b, c) \boxtimes R \boxtimes (a, c) \boxtimes R for all a, b, c \boxtimes A i.e. a R b and b R c \boxtimes a R c
- **(vii) Equivalence relation :** A relation R on a set A is said to be an equivalence relation on A iff
- (i) it is reflexive i.e. (a, a)

 R for all a

 A
- (ii) it is symmetric i.e. (a, b) ⋈ R ⋈ (b, a) ⋈ R for all a, b ⋈ A
- (iii) it is transitive i.e. (a, b) ⋈ R and (b, c) ⋈ R ⋈ (a, c) ⋈ R for all a,b⋈A